We Have a DREAM: Distributed Reactive Programming with Consistency Guarantees

Alessandro Margara, Guido Salvaneschi

Presented by Wilfried Daniels

- Designing, implementing and maintaining reactive systems is difficult
 - Asynchronous callbacks
 - Hard to trace/understand control flow
 - → Solution: Reactive Programming

- Key concepts:
 - time-varying values
 - tracking of dependencies
 - automatic propagation of changes
 - 1 var a: int = 10
 - 2 **var** b: int = a + 2
 - 3 println(b) // 12
 - $_{4} a = 11$
 - 5 println(b) // 12



- 1 var a: int = 10
- 2 **var** b: int = a + 2
- 3 println(b) // 12

$$_{4} a = 11$$

5 println(b) // 13



- Advantages vs. classic event-based arch:
 - No explicit update logic
 - Declarative specification of dependencies
 - Runtime manages correct propagation (e.g. glitch freeness/consistency)
- This work focuses on distributed reactive programming (DRP)

 Previous DRP solutions do not guarantee distributed consistency (only local)

 This paper presents DREAM , a Distributed REActive Middleware with three different levels of consistency guarantees

- Motivation for different levels of consistency
- Running example: financial application system

```
1 var marketIndex = InputModule.getMarketIndex()
                                                            Observable
2 var stockOpts = InputModule.getStockOpts()
                                                           time-varying variables
3 var news = InputModule.getNews()
4
5 // Forecasts according to different models
                                                            Dependent
6 var f1(=)Model1.compute(marketIndex,stockOpts)
7 var f2 := Model2.compute(marketIndex,stockOpts)
                                                           Reactive expressions
8 var f3 := Model3.compute(marketIndex,news)
9.___
or var gui := Display.show(f1,f2,f3)
                                                     V1
                                                            Reactive expressions
                                                           resulting in 3
2_1^{r} var financialAlert := ((f1+f2+f3)/3) < MAX
                                                     V2
                                                            alternative outputs,
3 if (financialAlert) decrease(stockOpts)
                                                           each requiring
5_1 var financialAlert_n := computeAlert_n(f1,f2,f3)
                                                     V3
                                                           different consistency
6 if (financialAlert_n) adjust_n(stockOpts)
                                                           guarantees
```

- Variant 1: Smartphone app
 - Just displays output of 3 models
 - No consistency required

var gui := Display.show(f1,f2,f3) V1

- Variant 2: Models aggregator
 - Aggregates output of 3 models
 - Undertakes action when below threshold

 $\begin{array}{c} \mbox{var financialAlert} := ((f1+f2+f3)/3) < MAX \\ \mbox{if (financialAlert) decrease(stockOpts)} \end{array} \begin{array}{c} V2 \\ \end{array}$

- Variant 2: Models aggregator
 - Requires glitch freedom
 - Assume initially **f1**:110, **f2**:95, **f3**:99 with **MAX**:100
 - New marketIndex: all models recalculate.
 - Model **f1** finishes first with **f1**: 90
 - → STOCKS DECREASED (GLITCH!)
 - Other models finish: **f2**:111, **f3**:103

```
\label{eq:var} \begin{array}{l} \mbox{financialAlert} := ((f1 + f2 + f3)/3) < MAX \\ \mbox{if (financialAlert) decrease(stockOpts)} \end{array} \begin{array}{l} \mbox{V2} \end{array}
```

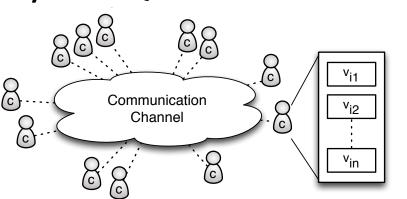
- Variant 3: Multiple aggregators
 - f1, f2, f3 are dispatched to n aggregators, that work autonomously
 - In case of deviating behaviour, any aggregator can adjust stockOpts
 - No glitch freedom required, but every single aggregator needs to see **f1**, **f2** and **f3** change in the same order

```
var financialAlert_n := computeAlert_n(f1,f2,f3)
if (financialAlert_n) adjust_n(stockOpts) V3
```

- Formal definition of DRP system architecture/ consistency guarantees
- **Components**: networked nodes in system

$$c_1 \ldots c_n$$

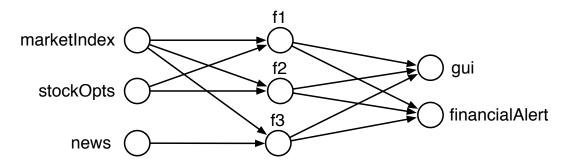
• Variables: state of component C_i is represented by $V_i = \{v_{i1} : \tau_{i1} \dots v_{im} : \tau_{im}\}$



- Besides traditional *imperative* variables, *reactive* and *observable* variables are defined
- **Reactive**: variable that is automatically updated based on reactive expression
- **Observable**: continuously changing var that is used to build expressions. Local or Global.
- e.g. stock market:

f3:= Model3.compute(marketIndex,news)

- Dependency Graph:
 - Directed graph $D = \{V, E\}$, where V is the set of all observable/reactive variables and E is the set of all edges that connect directly depending variables
 - E.g. stock market for Variant 1 + 2:



• Events:

- Write event: $w_x(v)$
 - Occurs when value x is written to variable v
- *Read* event: $r_x(v)$
 - Occurs when value x is read from variable v
- Update event: $u(S, w_x(v)), S = \{w_{y1}(v_1) \dots w_{yn}(v_n)\}$
 - Depending variable v is reactively update with value x due to the write events contained in the set S

- Consistency Guarantees
 - Exactly once delivery: ensures that, in absence of failure, the communication channel does not lose or duplicate an update. More formally:

If $w_x(v)$ occurs, then $u(S_i, w_y(v_i)), w_x(v) \in S_i$ occurs exactly once.

- Consistency Guarantees
 - FIFO ordering: changes to a a variable v in a componentc are propagated to depending reactive expressions in the same order they occur in c. More formally:

 $\forall v_i, v_j$, such that v_j depends on v_i , if $w_{x1}(v_i)$ occurs before $w_{x2}(v_i)$, then $u(S_1)$, $w_{x1}(v_i) \in S_1$ occurs before $u(S_2), w_{x2}(v_i) \in S_2$

- Consistency Guarantees
 - Causal ordering: ensures that events that are causally connected occur in every component in the same order. More formally:

We define a *happened before* (\rightarrow) partial order relation:

- If two events e_1, e_2 , occur in the same process, then $e_1 \rightarrow e_2$ if and only if e_1 occurs before e_2
- If $e_1 = w_x(v_i)$ and $e_2 = u(S_i, w_y(v_j)), w_x(v_i) \in S_i$, then $e_1 \to e_2$ (a write happens before an update depending on it)
- If $e_1 \rightarrow e_2$ and $e_2 \rightarrow e_3$, then $e_1 \rightarrow e_3$ (transitivity)
- No guarantees are made for events that are not causally connected!

- Consistency Guarantees
 - Glitch freedom: no partial updates due to propagation delays. More formally:

Consider the set V_d , containing all observable variables a reactive variable v depends on. Let us call $V_{d1} \subseteq V_d$ the set of variables that depend directly or indirectly from a variable v_1 . The update $u(S, w_x(v))$ is a *partial* update if $S \subset V_{d1}$. A glitch free system does not have partial updates.

- Consistency Guarantees
 - Atomic consistency: ensures that: (i) the system provides FIFO ordering, and (ii) every write event to an observable variable is atomically propagated to all (in)directly depending reactive variables. More formally:

All the update events $u(S_i, w_y(v_i))$ triggered (directly or indirectly) by $w_x(v)$ are executed as a single operation

– This is stricter than glitch freedom

- DREAM is entirely written in Java
- Observable variables \rightarrow observable objects
 - Inherit from Observable abstract class
 - All non-void methods: *observable* methods
 - Generic method *m* that potentially changes return value of observable method *obm*: *m* impacts *obm*
 - Impacts should be known by runtime
 - \rightarrow Java Annotations

Example of observable class representing an integer:

```
1 public class ObservableInteger extends Observable {
    private int val;
\mathbf{2}
3
    // Constructors ...
\mathbf{4}
5
     @ImpactsOn(methods = { "get" })
6
     public final void set(int val) {
\overline{7}
       this.val = val;
8
     }
9
10
   public final int get() {
11
       return val;
12
13
     }
14 }
```

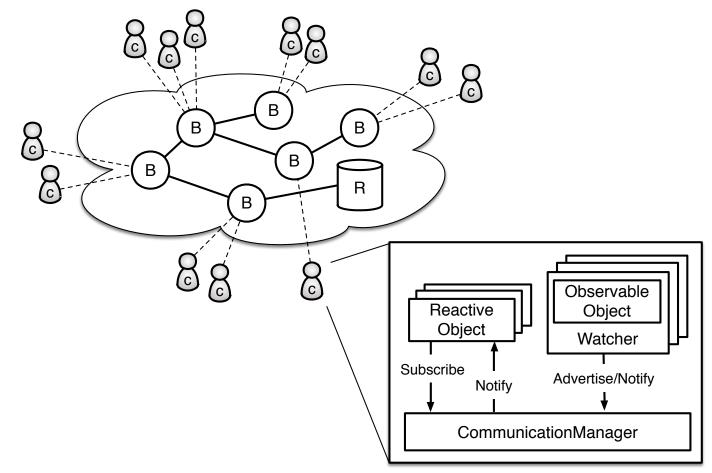
- Reactive variables \rightarrow Reactive objects
- Created by using the ReactiveFactory class
 - Parses reactive expressions (strings with ANTLR)
 - Reactive objects can be observable (optional)
- Naming space:
 - Unique name: c.obj.obm for observable method obm of object obj in component c
 - For local objects: obj.obm

• Example:

```
1 // Component c1
2 ObservableInteger obInt =
    new ObservableInteger("obInt1", 1, LOCAL);
 3
 4 ObservableString obStr1 =
    new ObservableString("obStr1", "a", GLOBAL);
 \mathbf{5}
6 ObservableString obStr2 = ...
 7
s // Component c2
9 ReactiveInteger rInt = ReactiveFactory.
    getInteger("obInt.get() *2");
10
11 ReactiveString rStr = ReactiveFactory.
    getString("obStr1.get()+obStr2.get()");
12
13 while (true) {
    System.out.println(rStr.get())
14
    Thread.sleep(500)
15
16 }
17
18 // Component c3
19 ReactiveInteger strLen =
    ReactiveFactory.get(bservableInteger
20
    ("c1.obString1.get().length()", ("obString1Len");
21
```

- Architecture consists of two parts:
 - A client library on every component
 - A distributed event-based infrastructure, consisting of *brokers*
- Brokers form an acyclic overlay network, offering communication between components
- Optional registry for persistence

• Architecture overview



• Pub-Sub Communication:

Clients register with brokers through 3 primitives:

- advertise(c,obj,obm): used by c if it has a
 globally observable method obj.obm()
- subscribe(c,obj,obm): used to register a component that has a reactive expression containing c.obj.obm()
- notify(c,obj,obm,val): used by c when obj.obm() has a new value val

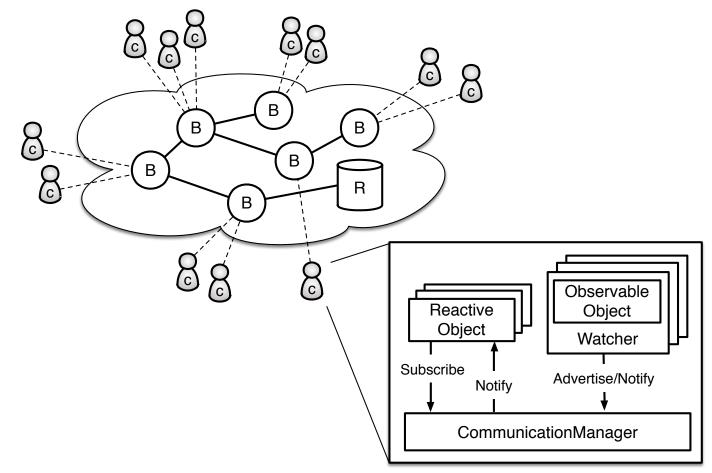
Clients

- CommunicationManager:
 - Proxy for global communication
 - Manage local communication
- Observable objects:
 - Have Watcher code woven in through AOP
 - Watcher interacts with CommunicationManager to:
 - 1. Advertise new objects through advertise(c,obj,obm)
 - 2. Detect changes to observables and propagate them out through notify(c,obj,obm,val)

• Clients

- Reactive Objects:
 - When instantiated, for all relevant observable methods
 → subscribe(c,obj,obm) with CommunicationManager
 - When new values available, notification from CommunicationManager

• Architecture overview



Brokers

Run REDS event dispatching

- Brokers are connected in acyclic graph
- Advertisements are propagated through graph + stored by all brokers, remembering next hop
- When a broker receives a subscription, store in table and forward to next hop (retrace path of advertisements)

- Consistency Guarantees
 - Causal ordering:
 - Use point to point TCP for broker-broker and clientbroker communication
 - Use single thread for FIFO event processing

→ These 2 properties with an acyclic topology are sufficient for causal ordering

- Consistency Guarantees
 - Glitch freedom:
 - New reactive object: push propagate expression to all brokers → each broker has dependency graph
 - When a chain of operations is triggered, always include the original write event that caused it in communications
 - Local communication has to go through a broker as well to ensure glitch freedom

→ This information is enough for the brokers to schedule propagation in a way that avoids partial updates

- Consistency Guarantees
 - Atomic ordering:
 - Adds centralized Ticket Granting Service (TGS)
 - When a write event occurs, *all* it's directly and indirectly dependent reactive expressions are reevaluated atomically (no other write operations)
 - On write: get ticket, wait in line and be served one at a time
 - → This entails glitch freedom and is an even stronger consistency guarantee

- Twofold:
 - Large scale emulation: Cost of DRP protocols with different levels of consistency guarantees/ varying parameters. KPIs:
 - Average propagation delay (ms)
 - Network wide traffic throughput (KB/s)
 - 2. Real-world runtime overheads

• Default values for emulation:

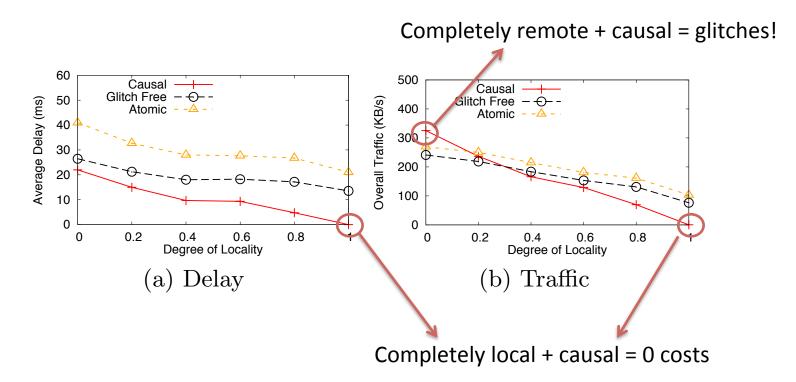
| Number of brokers | 10 |
|--|-----------------------------------|
| Number of components | 50 |
| Topology of broker network | Scale-free |
| Percentage of pure forwarders | 50% |
| Distribution of components | Uniform |
| Link latency | $1 \mathrm{~ms}{-}5 \mathrm{~ms}$ |
| Number of reactive graphs | 10 |
| Size of dependency graphs | 5 |
| Size of reactive expressions | 2 |
| Degree of locality in expressions | 0.8 |
| Frequency of change for observable objects | 1 change/s |

- Advantages of distribution
 - 1 broker vs. 10 brokers
 - Causal: no big impact mainly due to locality
 - Glitch free: *all* propagation through broker
 - \rightarrow Having multiple brokers helps
 - Atomic: adds TGS delay + traffic
 - \rightarrow Same advantages when multiple brokers

| | Delay (ms) | | Traffic (KB/s) | |
|-------------|------------|--------|----------------|--------|
| | Centr. | Distr. | Centr. | Distr. |
| Causal | 4.77 | 4.76 | 68.3 | 69.8 |
| Glitch free | 29.53 | 17.18 | 205.4 | 130.9 |
| Atomic | 53.41 | 26.75 | 265.5 | 161.3 |

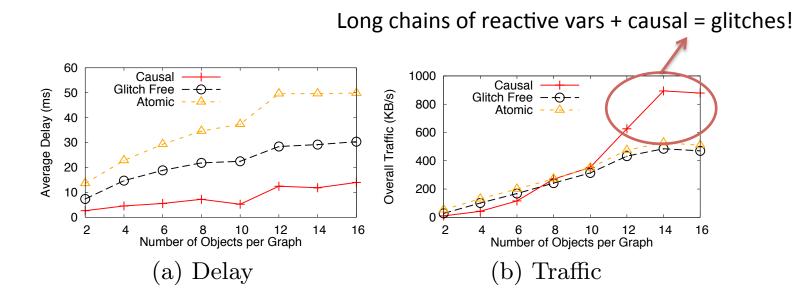
• Locality of expressions

- General trend: locality cuts costs

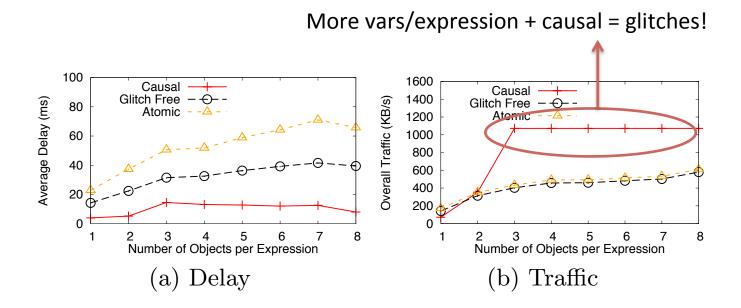


• Size of reactive graphs

- General trend: large reactive graphs increase costs



- Size of expressions
 - General trend: bigger expressions increase costs



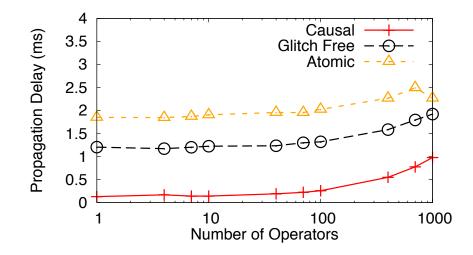
• Runtime overheads

– Overheads consisting of:

- Intercepting a method call
- Serializing/deserializing
- Propagating the change
- Evaluating reactive expression
- Local scenario: two clients and a broker on 1 machine, with increasing expression length

Runtime overheads

- Conclusion: runtime overheads are minimal



Conclusion

• Key contributions:

 First abstract model of DRP/formalizing consistency constraints

DREAM: a first DRP middleware supporting 3 propagation semantics

A thorough evaluation of the costs

Conclusion

- Future work:
 - A glitch free protocol that takes advantage of locality
 - Robustness in case of node failure
 - More complex expressions (time series and sequence of changes)
 - Different evaluation strategies (lazy, incremental) to improve efficiency
 - More real applications