### We Have a DREAM: Distributed Reactive Programming with Consistency Guarantees

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- Designing, implementing and maintaining reactive systems is difficult
  - Asynchronous callbacks
  - Hard to trace/understand control flow
  - → Solution: Reactive Programming

- Key concepts:
  - time-varying values
  - tracking of dependencies
  - automatic propagation of changes
    - 1 var a: int = 10
    - 2 **var** b: int = a + 2
    - 3 println(b) // 12
    - $_{4} a = 11$
    - 5 println(b) // 12



- 1 var a: int = 10
- 2 **var** b: int = a + 2
- 3 println(b) // 12

$$_{4} a = 11$$

5 println(b) // 13



- Advantages vs. classic event-based arch:
  - No explicit update logic
  - Declarative specification of dependencies
  - Runtime manages correct propagation (e.g. glitch freeness/consistency)
- This work focuses on distributed reactive programming (DRP)

 Previous DRP solutions do not guarantee distributed consistency (only local)

 This paper presents DREAM , a Distributed REActive Middleware with three different levels of consistency guarantees

- Motivation for different levels of consistency
- Running example: financial application system

```
1 var marketIndex = InputModule.getMarketIndex()
                                                            Observable
2 var stockOpts = InputModule.getStockOpts()
                                                           time-varying variables
3 var news = InputModule.getNews()
4
5 // Forecasts according to different models
                                                            Dependent
6 var f1(=)Model1.compute(marketIndex,stockOpts)
7 var f2 := Model2.compute(marketIndex,stockOpts)
                                                           Reactive expressions
8 var f3 := Model3.compute(marketIndex,news)
9.___
or var gui := Display.show(f1,f2,f3)
                                                     V1
                                                            Reactive expressions
                                                           resulting in 3
2_1^{r} var financialAlert := ((f1+f2+f3)/3) < MAX
                                                     V2
                                                            alternative outputs,
3 if (financialAlert) decrease(stockOpts)
                                                           each requiring
5_1 var financialAlert_n := computeAlert_n(f1,f2,f3)
                                                     V3
                                                           different consistency
6 if (financialAlert_n) adjust_n(stockOpts)
                                                           guarantees
```

- Variant 1: Smartphone app
  - Just displays output of 3 models
  - No consistency required

var gui := Display.show(f1,f2,f3) V1

- Variant 2: Models aggregator
  - Aggregates output of 3 models
  - Undertakes action when below threshold

 $\begin{array}{c} \mbox{var financialAlert} := ((f1+f2+f3)/3) < MAX \\ \mbox{if (financialAlert) decrease(stockOpts)} \end{array} \begin{array}{c} V2 \\ \end{array}$ 

- Variant 2: Models aggregator
  - Requires glitch freedom
  - Assume initially **f1**:110, **f2**:95, **f3**:99 with **MAX**:100
  - New marketIndex: all models recalculate.
  - Model **f1** finishes first with **f1**: 90
    - → STOCKS DECREASED (GLITCH!)
  - Other models finish: **f2**:111, **f3**:103

```
\label{eq:var} \begin{array}{l} \mbox{financialAlert} := ((f1 + f2 + f3)/3) < MAX \\ \mbox{if (financialAlert) decrease(stockOpts)} \end{array} \begin{array}{l} \mbox{V2} \end{array}
```

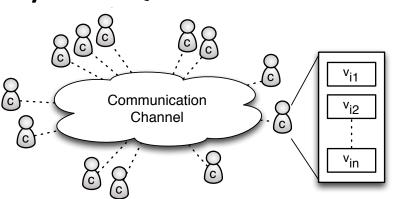
- Variant 3: Multiple aggregators
  - f1, f2, f3 are dispatched to n aggregators, that work autonomously
  - In case of deviating behaviour, any aggregator can adjust stockOpts
  - No glitch freedom required, but every single aggregator needs to see **f1**, **f2** and **f3** change in the same order

```
var financialAlert_n := computeAlert_n(f1,f2,f3)
if (financialAlert_n) adjust_n(stockOpts) V3
```

- Formal definition of DRP system architecture/ consistency guarantees
- **Components**: networked nodes in system

$$c_1 \ldots c_n$$

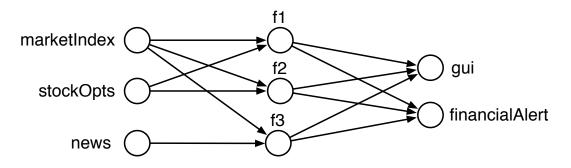
• Variables: state of component  $C_i$  is represented by  $V_i = \{v_{i1} : \tau_{i1} \dots v_{im} : \tau_{im}\}$ 



- Besides traditional *imperative* variables, *reactive* and *observable* variables are defined
- **Reactive**: variable that is automatically updated based on reactive expression
- **Observable**: continuously changing var that is used to build expressions. Local or Global.
- e.g. stock market:

f3:= Model3.compute(marketIndex,news)

- Dependency Graph:
  - Directed graph  $D = \{V, E\}$ , where V is the set of all observable/reactive variables and E is the set of all edges that connect directly depending variables
  - E.g. stock market for Variant 1 + 2:



#### • Events:

- Write event:  $w_x(v)$ 
  - Occurs when value x is written to variable v
- *Read* event:  $r_x(v)$ 
  - Occurs when value x is read from variable v
- Update event:  $u(S, w_x(v)), S = \{w_{y1}(v_1) \dots w_{yn}(v_n)\}$ 
  - Depending variable v is reactively update with value x due to the write events contained in the set S

- Consistency Guarantees
  - Exactly once delivery: ensures that, in absence of failure, the communication channel does not lose or duplicate an update. More formally:

If  $w_x(v)$  occurs, then  $u(S_i, w_y(v_i)), w_x(v) \in S_i$  occurs exactly once.

- Consistency Guarantees
  - FIFO ordering: changes to a a variable v in a componentc are propagated to depending reactive expressions in the same order they occur in c. More formally:

 $\forall v_i, v_j$ , such that  $v_j$  depends on  $v_i$ , if  $w_{x1}(v_i)$  occurs before  $w_{x2}(v_i)$ , then  $u(S_1)$ ,  $w_{x1}(v_i) \in S_1$  occurs before  $u(S_2), w_{x2}(v_i) \in S_2$ 

- Consistency Guarantees
  - Causal ordering: ensures that events that are causally connected occur in every component in the same order. More formally:

We define a *happened before*  $(\rightarrow)$  partial order relation:

- If two events  $e_1, e_2$ , occur in the same process, then  $e_1 \rightarrow e_2$  if and only if  $e_1$  occurs before  $e_2$
- If  $e_1 = w_x(v_i)$  and  $e_2 = u(S_i, w_y(v_j)), w_x(v_i) \in S_i$ , then  $e_1 \to e_2$ (a write happens before an update depending on it)
- If  $e_1 \rightarrow e_2$  and  $e_2 \rightarrow e_3$ , then  $e_1 \rightarrow e_3$  (transitivity)
- No guarantees are made for events that are not causally connected!

- Consistency Guarantees
  - Glitch freedom: no partial updates due to propagation delays. More formally:

Consider the set  $V_d$ , containing all observable variables a reactive variable v depends on. Let us call  $V_{d1} \subseteq V_d$  the set of variables that depend directly or indirectly from a variable  $v_1$ . The update  $u(S, w_x(v))$  is a *partial* update if  $S \subset V_{d1}$ . A glitch free system does not have partial updates.

- Consistency Guarantees
  - Atomic consistency: ensures that: (i) the system provides FIFO ordering, and (ii) every write event to an observable variable is atomically propagated to all (in)directly depending reactive variables. More formally:

All the update events  $u(S_i, w_y(v_i))$  triggered (directly or indirectly) by  $w_x(v)$  are executed as a single operation

– This is stricter than glitch freedom

- DREAM is entirely written in Java
- Observable variables  $\rightarrow$  observable objects
  - Inherit from Observable abstract class
  - All non-void methods: *observable* methods
  - Generic method *m* that potentially changes return value of observable method *obm*: *m* impacts *obm*
  - Impacts should be known by runtime
    - $\rightarrow$  Java Annotations

Example of observable class representing an integer:

```
1 public class ObservableInteger extends Observable {
    private int val;
\mathbf{2}
3
    // Constructors ...
\mathbf{4}
5
     @ImpactsOn(methods = { "get" })
6
     public final void set(int val) {
\overline{7}
       this.val = val;
8
     }
9
10
   public final int get() {
11
       return val;
12
13
     }
14 }
```

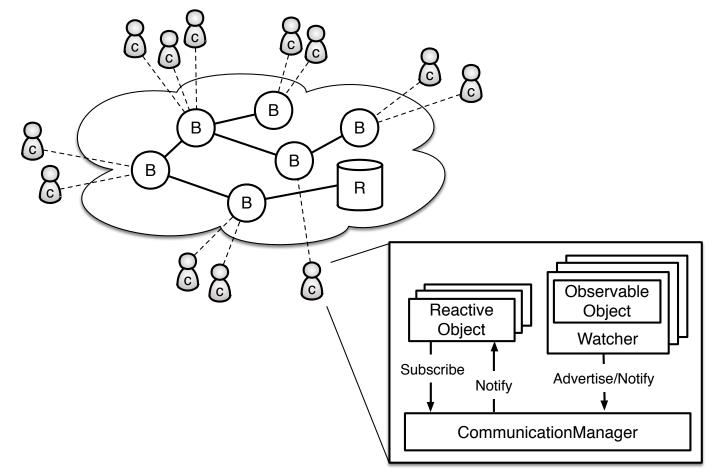
- Reactive variables  $\rightarrow$  Reactive objects
- Created by using the ReactiveFactory class
  - Parses reactive expressions (strings with ANTLR)
  - Reactive objects can be observable (optional)
- Naming space:
  - Unique name: c.obj.obm for observable method obm of object obj in component c
  - For local objects: obj.obm

#### • Example:

```
1 // Component c1
2 ObservableInteger obInt =
    new ObservableInteger("obInt1", 1, LOCAL);
 3
 4 ObservableString obStr1 =
    new ObservableString("obStr1", "a", GLOBAL);
 \mathbf{5}
6 ObservableString obStr2 = ...
 7
s // Component c2
9 ReactiveInteger rInt = ReactiveFactory.
    getInteger("obInt.get() *2");
10
11 ReactiveString rStr = ReactiveFactory.
    getString("obStr1.get()+obStr2.get()");
12
13 while (true) {
    System.out.println(rStr.get())
14
    Thread.sleep(500)
15
16 }
17
18 // Component c3
19 ReactiveInteger strLen =
    ReactiveFactory.get(bservableInteger
20
    ("c1.obString1.get().length()", ("obString1Len");
21
```

- Architecture consists of two parts:
  - A client library on every component
  - A distributed event-based infrastructure, consisting of *brokers*
- Brokers form an acyclic overlay network, offering communication between components
- Optional registry for persistence

• Architecture overview



• Pub-Sub Communication:

Clients register with brokers through 3 primitives:

- advertise(c,obj,obm): used by c if it has a
  globally observable method obj.obm()
- subscribe(c,obj,obm): used to register a component that has a reactive expression containing c.obj.obm()
- notify(c,obj,obm,val): used by c when obj.obm() has a new value val

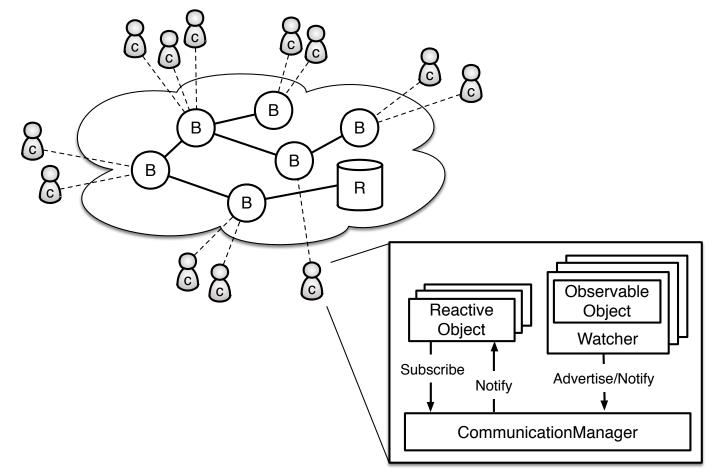
#### Clients

- CommunicationManager:
  - Proxy for global communication
  - Manage local communication
- Observable objects:
  - Have Watcher code woven in through AOP
  - Watcher interacts with CommunicationManager to:
    - 1. Advertise new objects through advertise(c,obj,obm)
    - 2. Detect changes to observables and propagate them out through notify(c,obj,obm,val)

#### • Clients

- Reactive Objects:
  - When instantiated, for all relevant observable methods
     → subscribe(c,obj,obm) with CommunicationManager
  - When new values available, notification from CommunicationManager

• Architecture overview



#### Brokers

Run REDS event dispatching

- Brokers are connected in acyclic graph
- Advertisements are propagated through graph + stored by all brokers, remembering next hop
- When a broker receives a subscription, store in table and forward to next hop (retrace path of advertisements)

- Consistency Guarantees
  - Causal ordering:
    - Use point to point TCP for broker-broker and clientbroker communication
    - Use single thread for FIFO event processing

→ These 2 properties with an acyclic topology are sufficient for causal ordering

- Consistency Guarantees
  - Glitch freedom:
    - New reactive object: push propagate expression to all brokers → each broker has dependency graph
    - When a chain of operations is triggered, always include the original write event that caused it in communications
    - Local communication has to go through a broker as well to ensure glitch freedom

→ This information is enough for the brokers to schedule propagation in a way that avoids partial updates

- Consistency Guarantees
  - Atomic ordering:
    - Adds centralized Ticket Granting Service (TGS)
    - When a write event occurs, *all* it's directly and indirectly dependent reactive expressions are reevaluated atomically (no other write operations)
    - On write: get ticket, wait in line and be served one at a time
    - → This entails glitch freedom and is an even stronger consistency guarantee

- Twofold:
  - Large scale emulation: Cost of DRP protocols with different levels of consistency guarantees/ varying parameters. KPIs:
    - Average propagation delay (ms)
    - Network wide traffic throughput (KB/s)
  - 2. Real-world runtime overheads

• Default values for emulation:

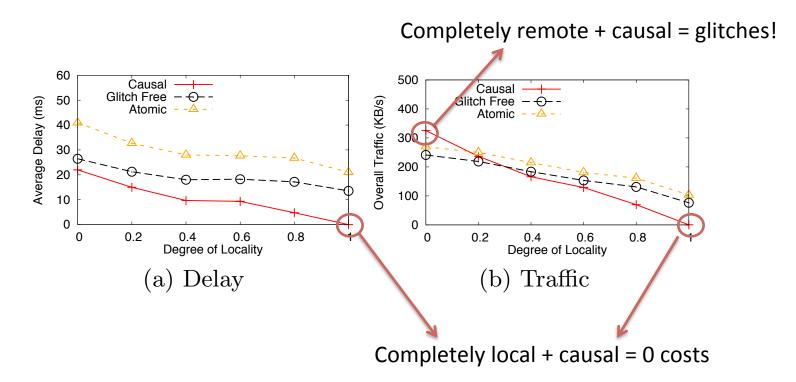
Number of brokers	10
Number of components	50
Topology of broker network	Scale-free
Percentage of pure forwarders	50%
Distribution of components	Uniform
Link latency	$1 \mathrm{~ms}{-}5 \mathrm{~ms}$
Number of reactive graphs	10
Size of dependency graphs	5
Size of reactive expressions	2
Degree of locality in expressions	0.8
Frequency of change for observable objects	1  change/s

- Advantages of distribution
  - 1 broker vs. 10 brokers
  - Causal: no big impact mainly due to locality
  - Glitch free: *all* propagation through broker
    - $\rightarrow$  Having multiple brokers helps
  - Atomic: adds TGS delay + traffic
    - $\rightarrow$  Same advantages when multiple brokers

	Delay (ms)		Traffic (KB/s)	
	Centr.	Distr.	Centr.	Distr.
Causal	4.77	4.76	68.3	69.8
Glitch free	29.53	17.18	205.4	130.9
Atomic	53.41	26.75	265.5	161.3

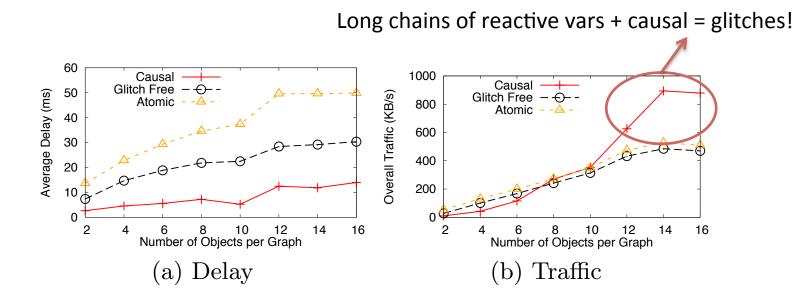
#### • Locality of expressions

- General trend: locality cuts costs

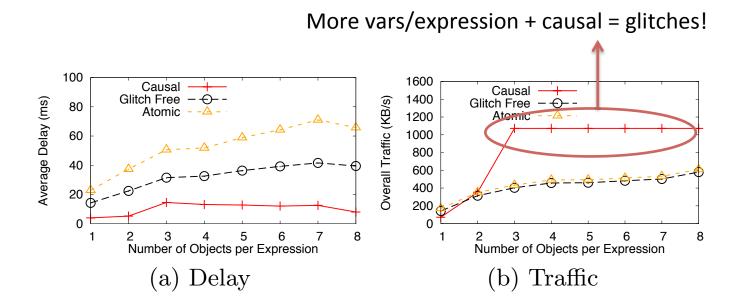


#### • Size of reactive graphs

- General trend: large reactive graphs increase costs



- Size of expressions
  - General trend: bigger expressions increase costs



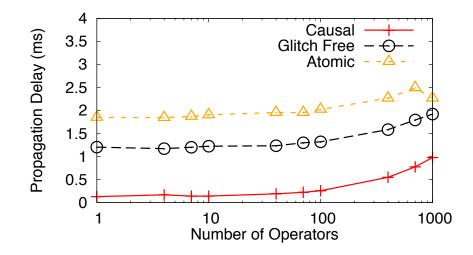
#### • Runtime overheads

– Overheads consisting of:

- Intercepting a method call
- Serializing/deserializing
- Propagating the change
- Evaluating reactive expression
- Local scenario: two clients and a broker on 1 machine, with increasing expression length

Runtime overheads

- Conclusion: runtime overheads are minimal



## Conclusion

• Key contributions:

 First abstract model of DRP/formalizing consistency constraints

DREAM: a first DRP middleware supporting 3 propagation semantics

A thorough evaluation of the costs

## Conclusion

- Future work:
  - A glitch free protocol that takes advantage of locality
  - Robustness in case of node failure
  - More complex expressions (time series and sequence of changes)
  - Different evaluation strategies (lazy, incremental) to improve efficiency
  - More real applications